

CSE 315

Microprocessors & Microcontrollers

Tanvir Ahmed Khan

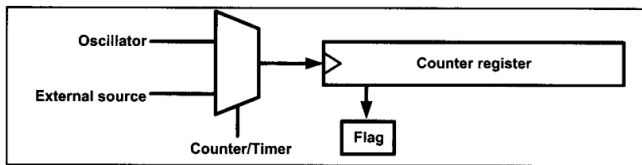
Department of Computer Science and Engineering
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September 13, 2014

Today's Topic

ATmega16 Timer/Counter

Timer/Counter Basics



Timer Basic

Two ways to generate a time delay,

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- ▶ clear the counter & wait until the counter reaches a certain number

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- ▶ clear the counter & wait until the counter reaches a certain number
- ▶ load the counter & wait until the counter overflows

Timer Basic

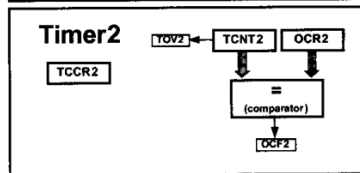
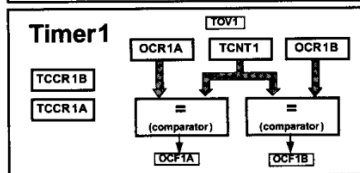
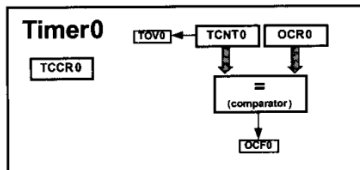
Two ways to generate a time delay,

- ▶ clear the counter & wait until the counter reaches a certain number
- ▶ **load the counter & wait until the counter overflows**

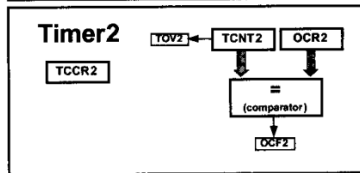
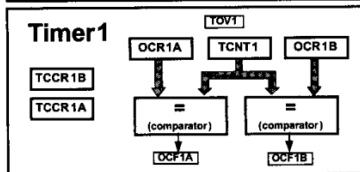
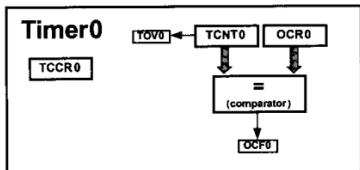
ATmega16 Timers

- ▶ Timer0, 8-bit
- ▶ Timer1, 16-bit
- ▶ Timer2, 8-bit

Timer Basic Registers



Timer Basic Registers



Timer/Counter Control Register (TCCR0)

FOC0	WGM00	COM01	COM00	WGM01	CS02	CS01	CS00
7							0

Timer/Counter Register (TCNT0)

7							0

Output Compare Register (OCR0)

7							0

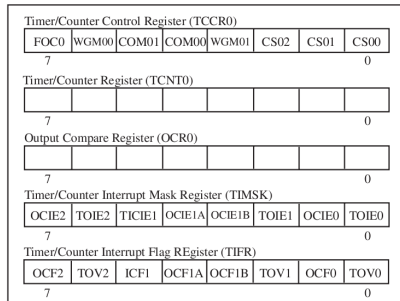
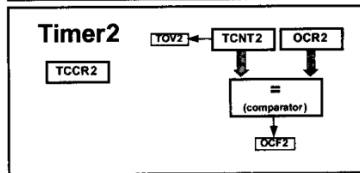
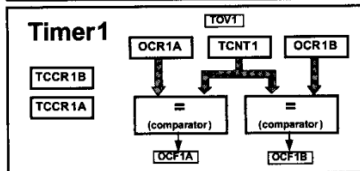
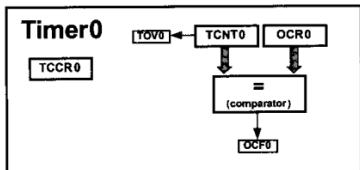
Timer/Counter Interrupt Mask Register (TIMSK)

OCIE2	TOIE2	ICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0
7							0

Timer/Counter Interrupt Flag Register (TIFR)

OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	OCF0	TOV0
7							0

Timer Basic Registers



CS02:00	D2	D1	D0	Timer0 clock selector
	0	0	0	No clock source (Timer/Counter stopped)
	0	0	1	clk (No Prescaling)
	0	1	0	clk / 8
	0	1	1	clk / 64
	1	0	0	clk / 256
	1	0	1	clk / 1024
	1	1	0	External clock source on T0 pin. Clock on falling edge.
	1	1	1	External clock source on T0 pin. Clock on rising edge.

Programming Timer0

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- ▶ Configure TCCR0,
 - ▶ `TCCR0 = 0b00000001;`

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- ▶ Configure TCCR0,
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- ▶ Load TCNT0 with initial value,
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- ▶ Check continuously TOV0,
 - ▶ `while((TIFR & 0b00000001) == 0);`

Programming Timer0

- ▶ Configure TCCR0,
 - ▶ `TCCR0 = 0b00000001;`
- ▶ Load TCNT0 with initial value,
 - ▶ `TCNT0 = 0b11110010;`
- ▶ Check continuously TOV0,
 - ▶ `while((TIFR & 0b00000001) == 0);`
- ▶ Stop the timer,
 - ▶ `TCCR0 = 0;`

Programming Timer0

- ▶ Configure TCCR0,
 - ▶ `TCCR0 = 0b00000001;`
- ▶ Load TCNT0 with initial value,
 - ▶ `TCNT0 = 0b11110010;`
- ▶ Check continuously TOV0,
 - ▶ `while((TIFR & 0b00000001) == 0);`
- ▶ Stop the timer,
 - ▶ `TCCR0 = 0;`
- ▶ Clear TOV0,
 - ▶ `TIFR = TIFR | 0b00000001;`

Simple Blink Example

```
4
5 #include <avr/io.h>
6
7 void delay(void){
8     int i,j;
9     for(i=0;i<100;i++)
10    {
11        for(j=0;j<100;j++)
12        {
13            asm volatile("nop");
14        }
15    }
16 }
17
18 int main(void)
19 {
20
21     DDRB = DDRB | 0b00000001;
22     PORTB = PORTB & 0b11111110;
23
24     while(1)
25     {
26         delay();
27         PORTB = PORTB ^ 0b00000001;
28     }
29     return 0;
30 }
31
```

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27         PORTB = PORTB ^ 0b00000001;
28     }
29     return 0;
30 }
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```

```
4
5 #include <avr/io.h>
6
7 void delay(void){
8     TCCR0 = 0b00000111;
9     TCNT0 = 0b00001111;
10    while((TIFR & 0b00000001) == 0);
11    TCCR0 = 0;
12    TIFR = TIFR | 0b00000001;
13 }
14
15 int main(void)
16 {
17
18     DDRB = DDRB | 0b00000001;
19     PORTB = PORTB & 0b11111110;
20
21     while(1)
22     {
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Practice Problems

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 - ▶ Clock = 8 MHz, TCNT0 = 0x3E, TCCR0 = 1
 - ▶ Clock = 8 MHz, TCNT0 = 0x00, TCCR0 = 5

Practice Problems

- ▶ Finding the delay for a specific TCNT0 value
 - ▶ Clock = 8 MHz, TCNT0 = 0x3E, TCCR0 = 1
 - ▶ Clock = 8 MHz, TCNT0 = 0x00, TCCR0 = 5
- ▶ Finding the value of TCNT0 for a specific delay

Practice Problems

- ▶ Finding the delay for a specific TCNT0 value
 - ▶ Clock = 8 MHz, TCNT0 = 0x3E, TCCR0 = 1
 - ▶ Clock = 8 MHz, TCNT0 = 0x00, TCCR0 = 5
- ▶ Finding the value of TCNT0 for a specific delay
 - ▶ Clock = 8 MHz, output signal frequency = 16 KHz

Practice Problems

- ▶ Finding the delay for a specific TCNT0 value
 - ▶ Clock = 8 MHz, TCNT0 = 0x3E, TCCR0 = 1
 - ▶ Clock = 8 MHz, TCNT0 = 0x00, TCCR0 = 5
- ▶ Finding the value of TCNT0 for a specific delay
 - ▶ Clock = 8 MHz, output signal frequency = 16 KHz
 - ▶ Clock = 8 MHz, output signal frequency = 125 Hz, with pre-scaler = 256

Reference

- ▶ The avr microcontroller & embedded system, *Chapter 9*
 - ▶ Muhammad Ali Mazidi
 - ▶ Sarmad Naimi
 - ▶ Sepehr Naimi