

CSE 315

Microprocessors & Microcontrollers

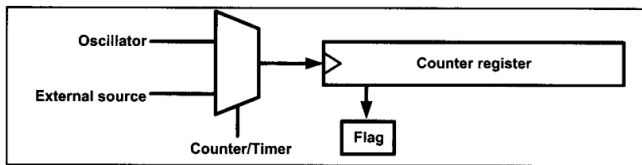
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Recap

Timer/Counter Basics



Timer Basic

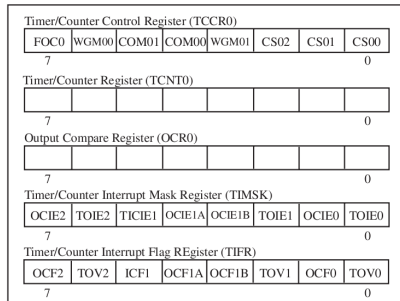
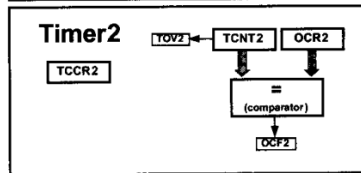
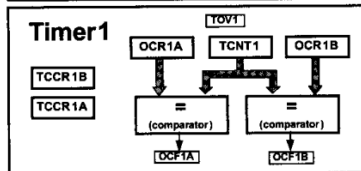
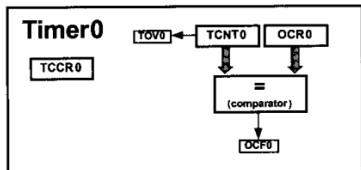
Two ways to generate a time delay,

- ▶ clear the counter & wait until the counter reaches a certain number
- ▶ **load the counter & wait until the counter overflows**

ATmega16 Timers

- ▶ Timer0, 8-bit
- ▶ Timer1, 16-bit
- ▶ Timer2, 8-bit

Timer Basic Registers



CS02:00	D2	D1	D0	Timer0 clock selector
	0	0	0	No clock source (Timer/Counter stopped)
	0	0	1	clk (No Prescaling)
	0	1	0	clk / 8
	0	1	1	clk / 64
	1	0	0	clk / 256
	1	0	1	clk / 1024
	1	1	0	External clock source on T0 pin. Clock on falling edge.
	1	1	1	External clock source on T0 pin. Clock on rising edge.

Programming Timer0

- ▶ Configure TCCR0,
 - ▶ `TCCR0 = 0b00000001;`
- ▶ Load TCNT0 with initial value,
 - ▶ `TCNT0 = 0b11110010;`
- ▶ Check continuously TOV0,
 - ▶ `while((TIFR & 0b00000001) == 0);`
- ▶ Stop the timer,
 - ▶ `TCCR0 = 0;`
- ▶ Clear TOV0,
 - ▶ `TIFR = TIFR | 0b00000001;`

Simple Blink Example

```
4
5 #include <avr/io.h>
6
7 void delay(void){
8     int i,j;
9     for(i=0;i<100;i++)
10    {
11        for(j=0;j<100;j++)
12        {
13            asm volatile("nop");
14        }
15    }
16 }
17
18 int main(void)
19 {
20
21     DDRB = DDRB | 0b00000001;
22     PORTB = PORTB & 0b11111110;
23
24     while(1)
25     {
26         delay();
27         PORTB = PORTB ^ 0b00000001;
28     }
29     return 0;
30 }
31
```

```
4
5 #include <avr/io.h>
6
7 void delay(void){
8     TCCR0 = 0b00000111;
9     TCNT0 = 0b00001111;
10    while((TIFR & 0b00000001) == 0);
11    TCCR0 = 0;
12    TIFR = TIFR | 0b00000001;
13 }
14
15 int main(void)
16 {
17
18     DDRB = DDRB | 0b00000001;
19     PORTB = PORTB & 0b11111110;
20
21     while(1)
22     {
23         delay();
24         PORTB = PORTB ^ 0b00000001;
25     }
26     return 0;
27 }
28
```


Practice Problems

- ▶ Finding the delay for a specific TCNT0 value
 - ▶ Clock = 8 MHz, TCNT0 = 0x3E, TCCR0 = 1
 - ▶ Clock = 8 MHz, TCNT0 = 0x00, TCCR0 = 5
- ▶ Finding the value of TCNT0 for a specific delay
 - ▶ Clock = 8 MHz, output signal frequency = 16 KHz
 - ▶ Clock = 8 MHz, output signal frequency = 125 Hz, with pre-scaler = 256

Today's Topic

ATmega16 Interrupt

Interrupts vs. Polling

Interrupts vs. Polling

- ▶ Efficiency

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- ▶ Monitoring several devices

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Interrupts vs. Polling

- ▶ Efficiency
- ▶ Monitoring several devices
- ▶ Priority
- ▶ Ignoring a device request

ATmega16 Interrupts

Vector No.	Program Address ⁽²⁾	Source	Interrupt Definition
1	\$000 ⁽¹⁾	RESET	External Pin, Power-on Reset, Brown-out Reset, Watchdog Reset, and JTAG AVR Reset
2	\$002	INT0	External Interrupt Request 0
3	\$004	INT1	External Interrupt Request 1
4	\$006	TIMER2 COMP	Timer/Counter2 Compare Match
5	\$008	TIMER2 OVF	Timer/Counter2 Overflow
6	\$00A	TIMER1 CAPT	Timer/Counter1 Capture Event
7	\$00C	TIMER1 COMPA	Timer/Counter1 Compare Match A
8	\$00E	TIMER1 COMPB	Timer/Counter1 Compare Match B
9	\$010	TIMER1 OVF	Timer/Counter1 Overflow
10	\$012	TIMER0 OVF	Timer/Counter0 Overflow
11	\$014	SPI, STC	Serial Transfer Complete
12	\$016	USART, RXC	USART, Rx Complete
13	\$018	USART, UDRE	USART Data Register Empty
14	\$01A	USART, TXC	USART, Tx Complete
15	\$01C	ADC	ADC Conversion Complete
16	\$01E	EE_RDY	EEPROM Ready
17	\$020	ANA_COMP	Analog Comparator
18	\$022	TWI	Two-wire Serial Interface
19	\$024	INT2	External Interrupt Request 2
20	\$026	TIMER0 COMP	Timer/Counter0 Compare Match
21	\$028	SPM_RDY	Store Program Memory Ready

Interrupts Service Routine

- ▶ program associated with the interrupt

Interrupt Vector Table

- ▶ group of memory locations holding the addresses of ISR

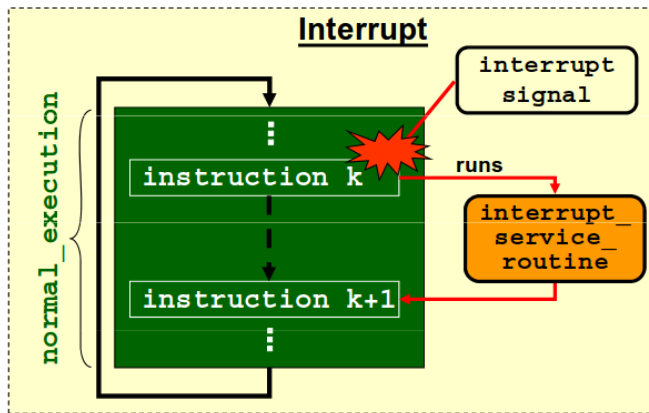
Interrupt Vector Table

- ▶ group of memory locations holding the addresses of ISR

Table 10-1: Interrupt Vector Table for the ATmega32 AVR

Interrupt	ROM Location (Hex)
Reset	0000
External Interrupt request 0	0002
External Interrupt request 1	0004
External Interrupt request 2	0006
Time/Counter2 Compare Match	0008
Time/Counter2 Overflow	000A
Time/Counter1 Capture Event	000C
Time/Counter1 Compare Match A	000E
Time/Counter1 Compare Match B	0010
Time/Counter1 Overflow	0012
Time/Counter0 Compare Match	0014
Time/Counter0 Overflow	0016
SPI Transfer complete	0018
USART, Receive complete	001A
USART, Data Register Empty	001C
USART, Transmit Complete	001E
ADC Conversion complete	0020
EEPROM ready	0022
Analog Comparator	0024
Two-wire Serial Interface (I2C)	0026
Store Program Memory Ready	0028

Interrupt Execution



Steps in Interrupt Execution

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- ▶ acknowledges the interrupt
- ▶ saves **P**rogram **C**ounter (also current context) onto stack
- ▶ jumps to *interrupt vector table* which redirects to the address of the **interrupt service routine**
- ▶ executes ISR upto *RETI* statement
- ▶ retrieves the original context and PC by popping the first byte of stack

Reference

- ▶ The avr microcontroller & embedded system, *Chapter 10*
 - ▶ Muhammad Ali Mazidi
 - ▶ Sarmad Naimi
 - ▶ Sepehr Naimi