

# CSE 315

## Microprocessors & Microcontrollers

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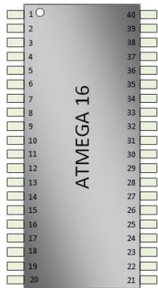
# Today's Topic

## Introduction to Embedded Systems

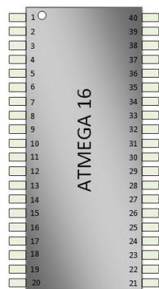
# Today's Main Objective

Building a counting system  
or  
Counter

# Our Magic Chip



# Our Magic Chip



- ▶  $V_{CC} \rightarrow 10$
- ▶  $GND \rightarrow 11$
- ▶ *PortB*,  $PB7 \rightarrow 8 - 1 \leftarrow PB0$
- ▶ *PortD*,  $PD7 \rightarrow 21 - 14 \leftarrow PD0$
- ▶ *PortC*,  $PC7 \rightarrow 29 - 22 \leftarrow PC0$
- ▶ *PortA*,  $PA7 \rightarrow 33 - 40 \leftarrow PA0$

# Digital I/O in ATmega16

- ▶ 4 8-bit digital IO ports, A, B, C, D
- ▶ Each port has 8 data pins
- ▶ Every **pin** is bidirectional

# Digital I/O in ATmega16

- ▶ 4 8-bit digital IO ports, A, B, C, D
- ▶ Each port has 8 data pins
- ▶ Every **pin** is bidirectional and can be configured as-
  - ▶ input (receiving data in mcu)
  - ▶ output (sending data from mcu)

# !!!Let Us C!!!

```
#include <stdio.h>
```

```
int main(void)
```

```
{
```

```
    printf(" Hello World!\n");
```

```
    return 0;
```

```
}
```



# Let Us C for Microcontrollers

```
#include <avr/io.h>
```

```
int main(void)
{
    while(1){}
    return 0;
}
```

# Digital I/O in ATmega16 Contd.

## Configuring Pins for Input & Output

- ▶ Relevant 8 bit Registers
  - ▶ Data Direction Register (**DDRx**), where,  $x = A, B, C, D$
- ▶ pin configuration,
  - ▶ input  $\rightarrow 0$
  - ▶ output  $\rightarrow 1$
- ▶ C Code Example,
  - ▶ `DDRA = 0b10101010;`

		o	i	o	i	o	i	o	i
DDRA		1	0	1	0	1	0	1	0
Pin	33	.					.	40	

# Digital I/O in ATmega16 Contd.

## Reading Input Data from Port

- ▶ Relevant 8 bit Registers
  - ▶ Input Pins Address (**PIN $x$** ), where,  $x = A, B, C, D$
- ▶ **What if some pins are configured as output?**
  - ▶ we get garbage value
  - ▶ so bit mask them before checking
- ▶ C Code Example,
  - ▶ `unsigned char ch;`  
`ch = PINA;`

# Digital I/O in ATmega16 Contd.

## Writing Output Data to Port

- ▶ Relevant 8 bit Registers
  - ▶ Data Register (**PORT $x$** ), where,  $x = A, B, C, D$
- ▶ **What if some pins are configured as input?**
- ▶ C Code Example,
  - ▶ `PORTA = 0b01010101;`

# Our Very Simple Counter

## Requirements

1. *PA0* connected with the push button
  - ▶ takes pulse input
2. *PORTB* connected with 8 LEDs
  - ▶ displays the number of given pulses

# Our Very Simple Counter

## The C Program

```
5 #include <avr/io.h>
6
7 int main(void)
8 {
9     unsigned char ch      = 0;
10    unsigned char counter = 0;
11
12    DDRA = 0b11111110;
13    DDRB = 0b11111111;
14
15    PORTB = counter;
16    while(1)
17    {
18        ch = PINA;
19        ch = ch & 1;
20
21        if(ch == 0)
22        {
23            //do nothing
24        }
25        else
26        {
27            counter += 1;
28            PORTB    = counter;
29        }
30    }
31    return 0;
32 }
```

# Our Very Simple Counter

## The C Program

```
5 #include <avr/io.h>
6
7 int main(void)
8 {
9     unsigned char ch      = 0;
10    unsigned char counter = 0;
11
12    DDRA = 0b11111110;
13    DDRB = 0b11111111;
14
15    PORTB = counter;
16    while(1)
17    {
18        ch = PINA;
19        ch = ch & 1;
20
21        if(ch == 0)
22        {
23            //do nothing
24        }
25        else
26        {
27            counter += 1;
28            PORTB    = counter;
29        }
30    }
31    return 0;
32 }
```

Can you report any problem?

# Our Very Simple Counter

## The C Program

```
5 #include <avr/io.h>
6
7 int main(void)
8 {
9     unsigned char ch      = 0;
10    unsigned char counter = 0;
11
12    DDRA = 0b11111110;
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14
15    PORTB = counter;
16    while(1)
17    {
18        ch = PINA;
19        ch = ch & 1;
20
21        if(ch == 0)
22        {
23            //do nothing
24        }
25        else
26        {
27            counter += 1;
28            PORTB   = counter;
29        }
30    }
31    return 0;
32 }
```

We have to add delay



# Our Very Simple Counter

## The *Delayed* C Program

### Version 1

```
4
5#include <avr/io.h>
6
7void delay(void){
8    int i,j;
9    for(i=0;i<1000;i++){
10       for(j=0;j<1000;j++){
11          asm volatile("nop");
12       }
13    }
14}
15
16int main(void)
17{
18    unsigned char ch    = 0;
19    unsigned char counter = 0;
20
21    DDRA  = 0b11111110;
22    DDRB  = 0b11111111;
23
24    PORTB = counter;
25    while(1)
26    {
27        ch = PINA;
28        ch = ch & 1;
29
30        if(ch == 0)
31        {
32            //do nothing
33        }
34        else
35        {
36            counter += 1;
37            PORTB  = counter;
38            delay();
39        }
40    }
41    return 0;
42}
```

# Our Very Simple Counter

## The *Delayed* C Program

### Version 1

```
4
5#include <avr/io.h>
6
7void delay(void){
8    int i,j;
9    for(i=0;i<1000;i++){
10       for(j=0;j<1000;j++){
11           asm volatile("nop");
12       }
13     }
14 }
15
16int main(void)
17{
18    unsigned char ch    = 0;
19    unsigned char counter = 0;
20
21    DDRA  = 0b11111110;
22    DDRB  = 0b11111111;
23
24    PORTB = counter;
25    while(1)
26    {
27        ch = PINA;
28        ch = ch & 1;
29
30        if(ch == 0)
31        {
32            //do nothing
33        }
34        else
35        {
36            counter += 1;
37            PORTB = counter;
38            delay();
39        }
40    }
41    return 0;
42 }
```

### Version 2

```
4
5#include <avr/io.h>
6#include <util/delay.h>
7
8int main(void)
9{
10    unsigned char ch    = 0;
11    unsigned char counter = 0;
12
13    DDRA  = 0b11111110;
14    DDRB  = 0b11111111;
15
16    PORTB = counter;
17    while(1)
18    {
19        ch = PINA;
20        ch = ch & 1;
21
22        if(ch == 0)
23        {
24            //do nothing
25        }
26        else
27        {
28            counter += 1;
29            PORTB = counter;
30            _delay_ms(1000);
31        }
32    }
33    return 0;
34 }
```

# Homework

- ▶ If input (taken from *PORTC*) is less than 100, send it to *PORTB*, otherwise, send it to *PORTD*
- ▶ Monitor bit 7 of *PORTB*, if it is 1, configure *PB4* as input; else change it to output

# Homework

- ▶ If input (taken from *PORTC*) is less than 100, send it to *PORTB*, otherwise, send it to *PORTD*
- ▶ Monitor bit 7 of *PORTB*, if it is 1, configure *PB4* as input; else change it to output
- ▶ *Not really homework, are they?*
- ▶ taken from the reference book, solve Example 7-1 to 7-25 (excluding 7-7), 7-33 to 7-35
- ▶ Our reference book, **The avr microcontroller & embedded system**
  - ▶ Muhammad Ali Mazidi
  - ▶ Sarmad Naimi
  - ▶ Sepehr Naimi

# What's next on Microcontrollers?

- ▶ The whole development cycle(**Self-Study?**)
  - ▶ Telecom Spares, Techshopbd, **Others**
  - ▶ **AVR Libc**, WinAVR, AVR Studio, Extreme Burner
- ▶ AVR **architecture** & memory
- ▶ Interrupt & timers
- ▶ Serial communications
- ▶ Analogue to digital converter
- ▶ Pulse width modulator
- ▶ Random thoughts on embedded systems

# What's next on CSE 315?

- ▶ Arithmetic co-processor (**booth, modified-booth?**)
- ▶ 8255 PPI (**already done?**)

# Real Homework

- ▶ Start looking for a project idea on embedded system
- ▶ Have a look at [this](#)